

5 REFERENCE NUMERALS LIST

1	Apparatus
2	Non-real timetable part
10 2.1	Operating/programming device
2.1a	Programming tool
2.1b	Diagnostic tool
2.1c	Control software
2.1d	Control HMI
15 2.2	robot code
2.3	SPC-code
2.4	G-code
2.5	Windows driver
2.6	Evaluating device
20 3	Real timetable part
3.1	Robot control
3.1a	Robot interpolator
3.2	SPC
3.2a	SPC interpolator
25 3.3	CNC
3.3a	CNC interpolator
4	TCP/IP protocol
5	Motion manager
5'	Sensor manager
30 5"	I/O manager
5 ⁽³⁾	Peripherals manager
5.1	Connection
5.2	Motion driver layer

5.2a-f	Driver
5.3	Upper intermediate interpolation layer
5.4	Manager core
5.5	Lower intermediate interpolation layer
5 6	Operational units
6.1a-g	Drives
6.2a-c	Power supplies
6.3, 6.3'	DSE
6.4	HRB
10 7	Bus data router
8.1, 8.2, 8.3	Bus
8.1a, 8.2a, 8.3a	Bus driver
A1-A9	Drive
I/O1, I/O2	Input/output equipment
15 IPO _i	Interpolation clock
n, n _i , n'	Natural number (1, 2, 3, ...)
PC	Personal computer
P1, P2	Peripheral
RTACC	Quartz cycle
20 S1-S7	Sensor
t _{tick} , t _{tick} '	System clock